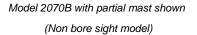
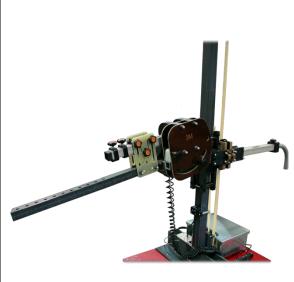
## Model 2070B / Model 2071B

# **Antenna Positioning Tower**

# **User Manual**







Model 2071B with partial mast shown
(Bore sight model)



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## Revision Record | MANUAL,2070B 2071B POSITIONING MAST | Part #399306, Rev. D

Revision	Description	Date
А	Initial Release	October, 2009
В	Added Model 2071B content	July, 2010
С	Added EC Declaration of Conformity; updated Assembly Steps	September, 2011
D	Updated height in <i>Specifications</i> ; updated measurements in <i>Boom Load Limitations</i> ; updated 114317 drawing in back of manual	March, 2013

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## **Notes, Cautions, and Warnings**

<b>→</b>	<b>Note:</b> Denotes helpful information intended to provide tips for better use of the product.
CAUTION	Caution: Denotes a hazard. Failure to follow instructions could result in minor personal injury and/or property damage. Included text gives proper procedures.
WARNING	Warning: Denotes a hazard. Failure to follow instructions could result in SEVERE personal injury and/or property damage. Included text gives proper procedures.



See the ETS-Lindgren Product Information Bulletin for safety, regulatory, and other product marking information.

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### 1.0 Introduction

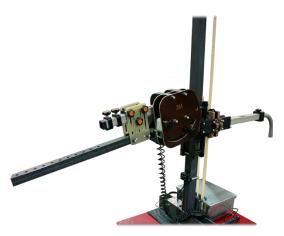
The ETS-Lindgren
Model 2070B (non bore sight)
and Model 2071B (bore sight)
Antenna Positioning Towers
are portable mast and platform
systems designed for use in
EMI compliance testing at
elevations from one to
four meters above the ground
level.

The mast, carrier, boom, platform, drive belts, and guying system are non-conductive and non-magnetic. The carrier is raised and lowered by a fractional horsepower electric motor with a gear reducer and electric brake. The electronics are contained in a shielded enclosure and the unit receives signals through fiber optic cables. The electric drive unit is located at the base of the tower.



Model 2070B non bore sight (partial mast shown)

The single-piece mast is constructed of square fiberglass tubing for strength, rigidity, and weatherability. Mylar rope guy lines are provided for outdoor installations and must be firmly anchored to provide vertical stability. The carrier is made of non-metallic material, primarily nylon and delrin.



Model 2071B bore sight (partial mast shown)

The motor system drives the carrier up and down using a polyurethane KEVLAR® reinforced timing belt. Rollers on the carrier provide friction-free, smooth travel. The motor typically positions the carrier within two centimeters of the desired location.

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Fiber optic limit switches mechanically limit the travel of the carrier. The upper limit is at a fixed location to stop the carrier at its maximum height. The lower limit is adjustable to fit test requirements. In addition, the Model 2090 Series Multi-Device Controller allows programming two upper and two lower limit settings. For more information on the Model 2090, see page 11.

The Model 2070B/2071B features centerline air polarization, which enhances measurement accuracy.

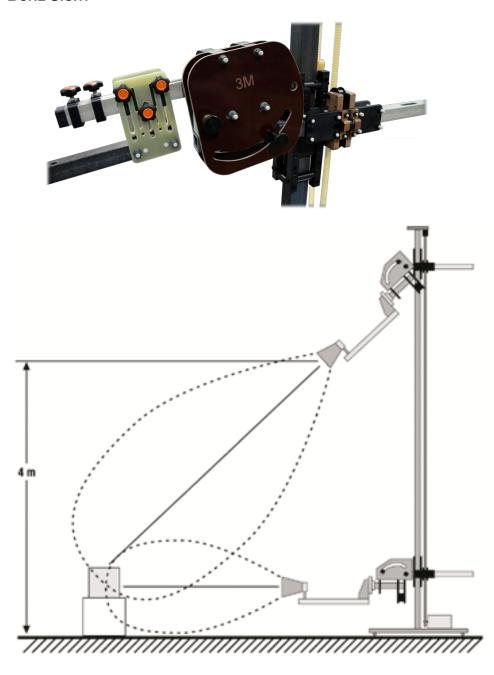
See *Mounting Antennas* on page 42 for information on the types of antenna mounts accepted by the Model 2070B/2071B.

### **About Bore Sight**

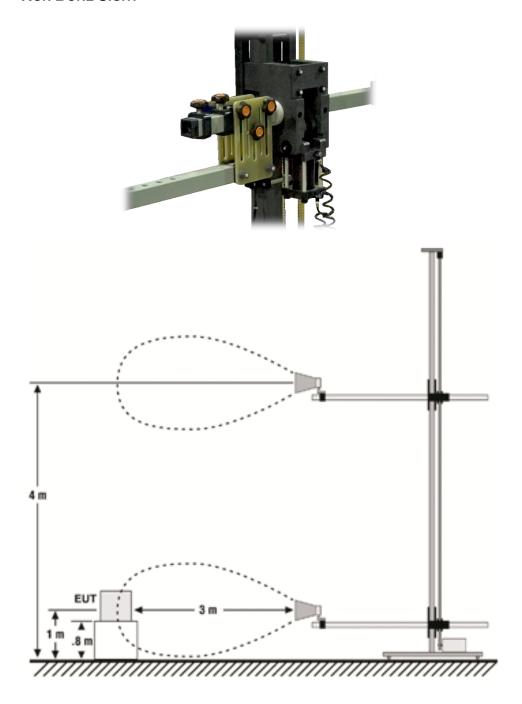
The Model 2071B provides the ETS-Lindgren patented bore sight system to provide direct antenna aim on Equipment Under Test (EUT) during scanning. This bore sight meets the requirements of ANSI C63.4 2003 and 2009 for compliance with FCC measurements above 1 GHz.

During scans, the bore sight system maintains constant directional antenna positioning while varying the angle between the antenna and the mast. This is particularly important when using higher gain antennas of more than 3 dBi. As the antenna is raised above the ground, the tilting of the antenna will maintain the EUT within the half power (-3 dB) beamwidth.

## **BORE SIGHT**



## Non Bore Sight



## **Standard Configuration**

Feature	Model 2070B (Non Bore Sight)	Model 2071B (Bore Sight)
Variable Speed Motor, 220V Single Phase Input	☑	☑
Castered Platform for Portability	N	$\square$
Single-Piece Mast for Rigidity	N	$\square$
Fixed Boom with Centerline Pneumatic Polarization		_
Bore Sight with Centerline Pneumatic Polarization	_	☑
Infrared (IR) Remote Controller (see page 39)		
10-Meter Fiber Optic Control Cable	8	$\square$
Fiber Optic Shield Room Penetration Kit routes the fiber optic control cable from the control room to the shield room while maintaining shielding attenuation. The pieces are made of brass for conductivity and provide attenuation of greater that 100 dB at 10 GHz. A single 25-mm (1.0-in) hole is required for mounting.		<b>\</b>

### **Optional Items**

## MODEL 2090 SERIES MULTI-DEVICE CONTROLLER



The Model 2090 (or next generation ETS-Lindgren controller, if applicable) is a separate component required for Model 2070B/2071B operation.

The Model 2090 requires firmware revision 3.12 or higher.

The Model 2090 Series Multi-Device Controller provides control for two separate devices, such as ETS-Lindgren towers and turntables, plus the control of four auxiliary devices through a fiber optic interface. The Model 2090 includes a GPIB bus and is compatible with most popular EMI measurement software.

### **ADDITIONAL FIBER OPTIC CABLE**

Various lengths of fiber optic cable are available by custom order. The standard length provided is 10 m (32.8 ft).

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## **ETS-Lindgren Product Information Bulletin**

See the ETS-Lindgren *Product Information Bulletin* included with your shipment for the following:

- Warranty information
- Safety, regulatory, and other product marking information
- Steps to receive your shipment
- Steps to return a component for service
- ETS Lindgren calibration service
- ETS Lindgren contact information

## **WARNING**

Before performing any maintenance, follow the safety information in the ETS-Lindgren *Product Information Bulletin* included with your shipment.



Do not attempt to service this unit until all electrical power has been disconnected.



This equipment should be operated and maintained by qualified personnel.

Disconnect all air supply lines when servicing pneumatic components.

Service equipment in accordance with the maintenance schedule provided.

Periodically check guy ropes and belt for wear.



Do not make any modifications to this unit without consulting the factory directly.

Only use replacement parts and fasteners ordered directly from the factory.

Maintenance of the Model 2070B and Model 2071B Antenna Positioning Towers is limited to the instructions provided in the next section, *Maintenance Schedule*. If you have any questions concerning maintenance, contact ETS-Lindgren Customer Service.

### **Maintenance Schedule**

#### **EVERY THREE MONTHS**

- Inspect belt for wear, tension, and cracking.
- Check all screws and bolts to confirm that are tight per assembly instructions.
- Inspect bolts and hardware for breakage.

Maintenance 13

### **EVERY SIX MONTHS**

- Check guy ropes for tightness, cracking, and delamination, if applicable.
- Check connecting control and all cables for degradation from environment and use. If necessary, replace per safety per local electrical codes.

### **EVERY TWELVE MONTHS**

Use high-grade silicone grease on all carrier rollers and the encoder center shaft (located inside motor cover).

## **Service Procedures**

For the steps to return a system or system component to ETS-Lindgren for service, see the *Product Information Bulletin* included with your shipment.

## 3.0 Specifications

## **Electrical Specifications**

Voltage:	220
Amp:	4.0
Line Frequency:	50/60
Phase:	Single

## **Physical Specifications**

Polarization:	30° per second	
Scan Height:	4.0 m (157.48 in)	
Weight (approximate):	79.38 kg (175.0 lb)	
Cross-Boom Loading:	10.4 kg (23.0 lb)	
Linear Velocity:	3 cm/sec-22 cm/sec	
Overall Height:	<ul> <li>Model 2070B: 4.6 m (180.7 in)</li> <li>Model 2071B: 5.2 m (204.4 in)</li> </ul>	
Base Dimensions:	1.1 m (42.5 in) x 0.9 m (35.5 in)	

Specifications | 15

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## 4.0 Electrical Installation

## **WARNING**

Before installing any components, follow the safety information in the ETS-Lindgren Product Information Bulletin included with your shipment.



Electrical installation must be performed by a qualified electrician, and in accordance with local and national electrical standards.



Make sure the power is off and secured before proceeding.

### Wire Gauge

Whenever possible the motor should be powered from a separate branch circuit of adequate capacity to keep voltage drop to a minimum during startup and running. For longer runs, increase the wire size in accordance with the following wire selection guide.



Never use smaller than 14 AWG for any installation.

Length of Wire	0-15.24 m	15.24-30.48 m	30.48-60.96 m
@ 220 V:	(0-50 ft)	(50-100 ft)	(100-200 ft)
Wire Gauge Required:	14 AWG	14 AWG	14 AWG

Electrical Installation 17

### **Power Cord**

The motor base is provided with an input AC power cord that is approximately 2.45 m (8 ft) long. This power cord is suitable for portable or indoor applications without modification.

### Connecting the Model 2090

Any combination of primary devices (towers, turntables, reverberation paddles, MAPS, and so on) can be connected to the two device interface ports located on the rear panel of the Model 2090 Series Multi-Device Controller. For easy set up of an EMC facility, it is recommended that the Model 2070B and Model 2071B Antenna Positioning Towers be connected to the **Device 1** port. The default settings are for a tower connected to the **Device 1** port and a turntable connected to the **Device 2** port.

Primary device connection is accomplished with a dual fiber optic cable included with the device. This cable terminates into two ST connectors that are identical at both ends. The cable is symmetrical, so either end can be connected to the Model 2090. A fiber optic cable connected to the IN port of a device should be connected to the primary OUT port of the motor base at the other end. Similarly, a fiber optic cable connected to the OUT port of the device should be connected to the primary IN port of the motor base at the other end. Older motor base designs have only one fiber optic connector pair, but the newer motor base interface provides a secondary interface reserved for future expansion.

CAUTION

Fiber optic cabling for each device should not hang unsupported from the rear panel of the Model 2090. The fibers and connectors are easily broken if twisted or bent. Keep the fiber optic cables as straight as possible from the connector to the protective sheath.

## 5.0 Assembly Instructions

## **WARNING**

Before connecting any components, follow the safety information in the ETS-Lindgren *Product Information Bulletin* included with your shipment.



This equipment should be installed, operated, and maintained by qualified personnel.



Stay clear of all moving components on this equipment.

Never stand beneath the carrier, whether moving or stationary.



See the ETS-Lindgren *Product Information Bulletin* included with your shipment for information on unpacking and acceptance procedures.

The Model 2070B and Model 2071B Antenna Positioning Towers should be assembled in the location where it will be used. If movement to another location is required after assembly, partial disassembly will be required for it to fit through most doorways.

### **Required Tools**

- 300 mm adjustable wrench (included)
- 3/16-in Allen wrench (hex key)
- Sawhorse or work bench
- Medium-sized level

## **Assembly Steps**

## **CAUTION**

### DO NOT DAMAGE FIBER OPTIC CABLES

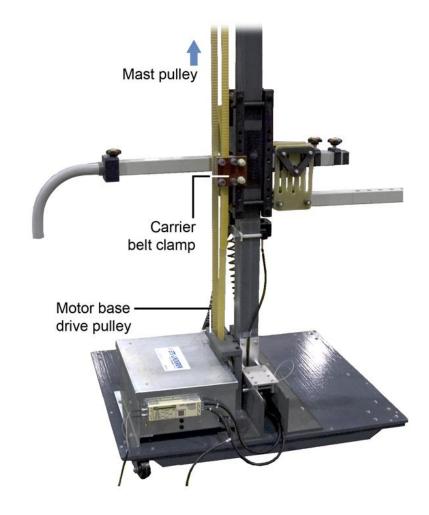
- During assembly do not pinch or damage the fiber optic cables.
- When inserting the mast into the lower mast section on the base, do not pinch or damage the fiber optic cables.
- When installing the mast locking pin, do not pinch or damage the fiber optic cables.



For illustrative purposes, the photos in this section show the Model 2070B/2071B partially and/or fully assembled. Follow the steps to assemble the Model 2070B/2071B.

- 1. Place the base of the Model 2070B/2071B in the chamber or other designated installation location.
- **2.** Place the mast horizontally onto an elevated, stable surface, such as sawhorses.

- **3.** Carefully slide the carrier unit onto the mast. Orient the carrier so that when the mast is inserted into the base:
  - The carrier belt clamp will be directly over the drive pulley on the motor base; and
  - The carrier belt clamp is in line with the mast pulley.



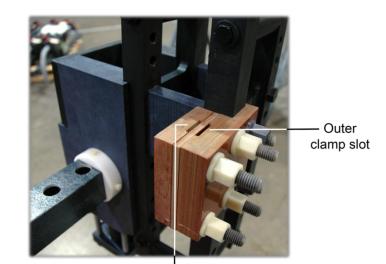
Assembly Instructions 21

4. Install the drive belt with the teeth facing each other.

Drive belt with teeth facing inward

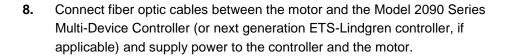
Feed the belt up through the outer clamp slot on the carrier belt clamp, around the mast pulley, and back down so both ends of the belt can be accessed when the tower is vertical. Leave approximately 0.5 m (1.5 ft) on both ends of the belt.

Temporarily tape the two ends together so the drive belt does not slide out of the pulley while the mast is being raised.



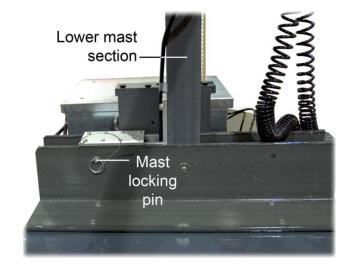
Inner clamp slot —

- Remove the mast locking pin and pivot the lower mast section down and horizontal to the floor.
- 6. With the mast and lower mast section in horizontal position, insert the mast into the lower mast section, aligning the pulley at the top of the mast with the pulley on the motor.
- **7.** Raise the mast and lower mast section to a vertical position and re-insert the mast locking pin.



The fiber optic cable must be looped through the P clip installed on the front panel of the motor base. Failure to do so will increase the chance of the fiber optic cable being accidentally pulled and breaking the fiber optic connectors and/or causing damage to the cable.

If you have a hand-held controller, you may connect it at this time.





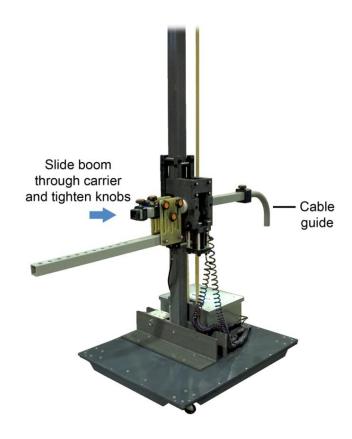
### **9.** Attaching the boom:

### MODEL 2070B ONLY

**TIP** | Run the antenna cables through the boom sections while assembling the boom. Be careful not to pinch or damage the cables.

Attached to one end of the boom unit is a cable guide that reduces the stress on the antenna feed cable; this cable guide must be removed to install the boom.

- Remove the bolts that hold the cable guide in place, and set the unit to the side.
- Slide the end of the boom where the cable guide was attached through the receptacle hole on the carrier so that the cable guide will be on the same side of the tower as the motor base.
- When the center block reaches the carrier, tighten the hand knobs to secure the boom in place.
- Reinstall the cable guide.

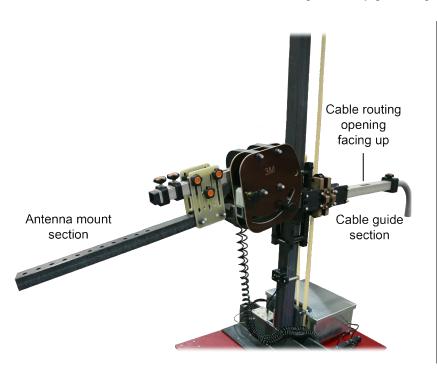


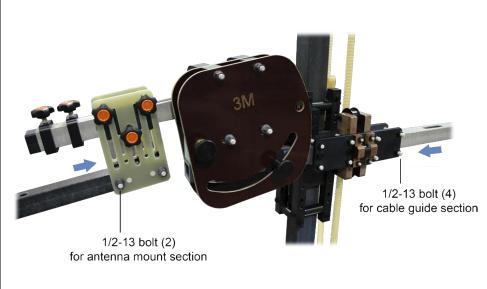
#### MODEL 2071B ONLY

**TIP** | Run the antenna cables through the boom sections while assembling the boom. Be careful not to pinch or damage the cables.

The boom assembly ships with the antenna mount section separated from the cable guide section. To assemble and install the boom:

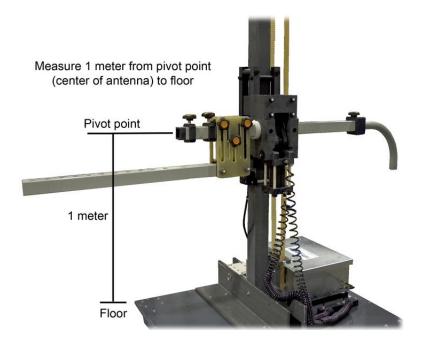
- Install cable guide section: Loosen the four 1/2–13 bolts, and then slide the cable guide section into the boom slot, making sure that the cable routing opening is facing up. Re-tighten the four bolts.
- **Install antenna mount section:** Remove the two 1/2–13 bolts from the carrier, and then slide the antenna mount section into the boom slot. Re-insert the two bolts, making sure they go through the antenna mount section. Tighten the two bolts.



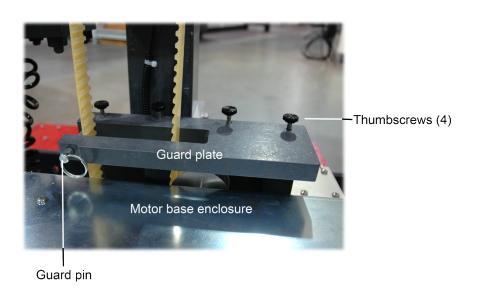


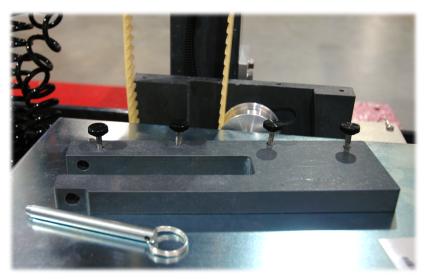
Assembly Instructions 25

**10.** Block the carrier so that the reference point on the largest antenna you use will be set at one meter. Place a piece of wood under the carrier to support it at this height.



**11.** Remove the guard plate located behind the motor base enclosure. Rotate the four thumbscrews to loosen the guard plate, remove the guard pin, and then lift the plate to remove it.

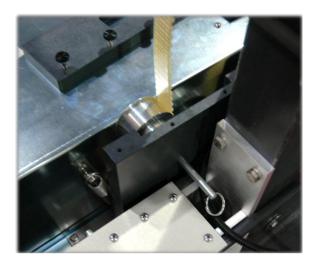




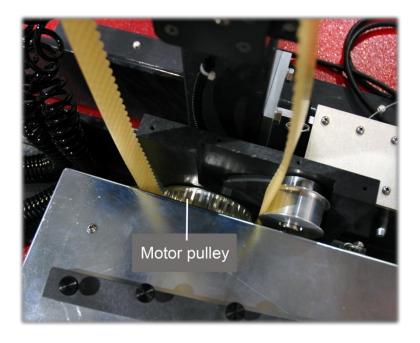
Assembly Instructions 27

12. Remove spring tension by carefully pulling back the belt tension idler on the motor base. While holding back the belt tension idler, insert the guard pin through the hole on the back of the guard plate enclosure to secure it in place.





13. Continue routing the drive belt down and around the motor pulley and up through the inner clamp slot on the carrier belt clamp (see photo of inner clamp slot on page 22) until approximately 0.5 m (1.5 ft) of belt is through the clamp. Remove the tape you placed on the drive belt in step 4.

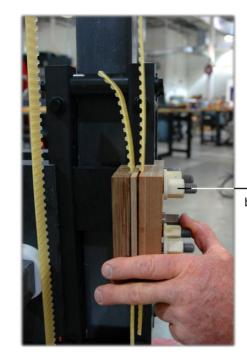


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## **14.** Hand-tighten the drive belt:

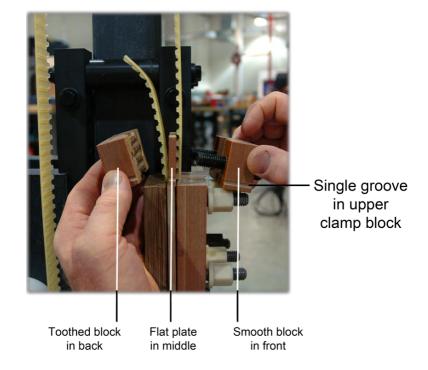
- Loosen the four bolts on the carrier belt clamp.
- Grasp both ends of the drive belt and pull them in opposite directions until the belt is as taut as possible.
- Re-tighten the four bolts on the carrier belt clamp.



Carrierbelt clampbolts(4)

- **15.** Install the upper clamp block (the one with a single groove etched in the side) to lock one end of the drive belt in place. The upper clamp block is comprised of three parts; assemble the parts as follows on top of the carrier belt clamp:
  - Place the flat plate between the drive belt and drive belt end.
  - Place the smooth block on the outside of the drive belt with the drive belt between the smooth block and the flat plate.
  - Place the toothed block on the other side of the flat plate with the drive belt end between the toothed block and the flat plate.

Insert two bolts through the smooth block and into all three parts; tighten.



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**16.** Install the lower clamp block (the one with two grooves etched in the side) to lock one end of the drive belt in place.

Like the upper clamp block, the lower clamp block is comprised of three parts. Assemble it like the upper clamp block, but place the parts below the carrier belt clamp.

Tighten the two bolts on the lower clamp block.



·Two grooves on lower clamp block

17. Loosen the four bolts on the carrier belt clamp.

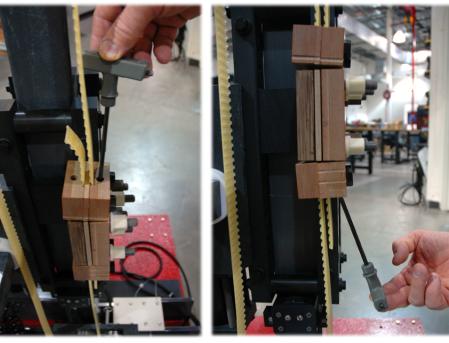
18. Using a 3/16-in Allen wrench (hex key), tension the drive belt with approximately 100-150 lb of pull on each end.

Insert the Allen wrench into the hole in the front of the upper clamp block, and then into the hole in the lower clamp block.





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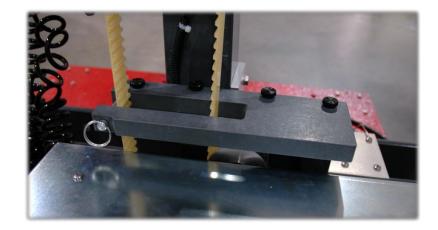


Assembly Instructions Archived 06/24/14

**19.** Re-tighten the four bolts on the carrier belt clamp using 11 N-m (100 in-lb) torque. Insert the four jam nuts and use approximately 7 N-m (60 in-lb) on the jam nuts.



**20.** Remove the guard plate pin from the back of the guard plate enclosure and replace the guard plate. Tighten the four thumbscrews and insert the pin in the front of the guard plate.

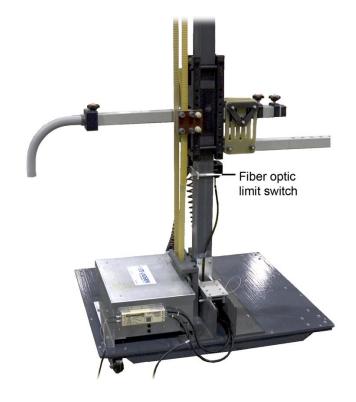


**CAUTION** 

The fiber optic limit switch is designed to stop the boom from traveling beyond a safe distance and causing damage to the Model 2070B/2071B. You must implement additional safeguards to prevent damage to any antenna installed on the Model 2070B/2071B.

## 21. To install the fiber optic limit switch:

- With the carrier at 1 meter, clamp the fiber optic limit switch assembly to the mast.
- Slide the fiber optic limit switch to the 1 meter position.



- 22. Carefully move the belt tension idler into place against the drive belt and re-install the spring if it was removed. The tension idler should be free on its pivot and the spring should force it against the belt.
- 23. With the proper belt tension and with no load on the boom, the idler should be stopped at approximately 30 mm (1.2 in) from reaching the end of travel against the motor pulley.

If the idler is against the pulley, retighten the belt to prevent slack when loads are applied to the boom. As the boom is loaded the tension idler needs to move closer and take up the slack as the mast deflects under load.

# **Air Polarization Assembly**

The automated air polarization assembly includes variable speed polarization cycling using flow control valves. The air cylinder is made of non-conductive material and will polarize the largest antenna recommended for the tower. The polarization speed range is 3° to 30° per second.

An air supply of 414-551 kPa (60-80 psi) is needed for this feature. It is important to have clean and dry air; so we recommend the use of a 40 micron filter in close proximity to the motor base.

Ten meters of UV stabilized air hose is included as well as a 1/8 inch NPT fitting. A metric fitting for a 4 mm tube may be supplied by the customer.

To connect the air line to the motor base, simply push the hose provided onto the fitting on the front of the motor base. The air supply pressure should be 414-551 kPa (60-80 psi). The air cylinder uses a special O-ring lubricant; during maintenance this lubricant should be applied to prevent excessive wear of the O-rings.

Assembly Instructions 37

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# **WARNING**

Before placing into operation, follow the safety information in the ETS-Lindgren *Product Information Bulletin* included with your shipment.



This equipment should be installed, operated, and maintained by qualified personnel.

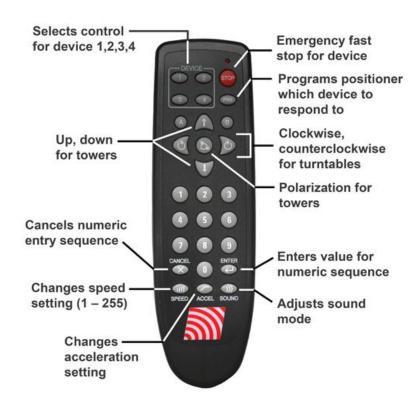


Stay clear of all moving components on this equipment.

Never stand beneath the carrier, whether moving or stationary.

### **Infrared Remote Controller**

The Model 2070B and Model 2071B Antenna Positioning Towers are infrared compatible, and can be used with a universal remote control programmed to a specific protocol, such as the ETS-Lindgren Infrared (IR) Remote Controller (included).



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If you are unfamiliar with the operation of the Model 2090 (or next generation ETS-Lindgren controller, if applicable), see the manual included with the controller. The manual is also available for download from www.ets-lindgren.com.

With the assembly of the tower complete, the controller must be connected to the unit and power applied to both the motor base and controller. See the controller manual for information on connecting the fiber optic cable.

Use the controller to check the clockwise (CW) and counterclockwise (CCW) rotation in both directions by a few degrees. The position in degrees increases (+) in the CW direction and decreases (-) in CCW direction.

### **EDIT CONFIGURATION PARAMETERS**

Key	Function		
PARAM	To edit a configuration parameter:		
	<ul> <li>Press PARAM key to display the current parameter.</li> </ul>		
	<ul> <li>Press PARAM key repeatedly to scroll through the parameter list, displaying each parameter.</li> </ul>		
STEP (INC/DEC)	To scroll up or down the parameter list while viewing a parameter. Reduces the effort necessary to scan through a long parameter list using the PARAM key.		
LIMIT/POSITION	Press any of the LIMIT/POSITION selection keys to return the display to that selection.		
	Press any of the remaining motion keys to return the display to the current position and execute that motion.		
	Press the PARAM key again to return to the last displayed parameter in the list, allowing easy transition between parameter adjustment and device operation.		

Key	Function
INCRM, DECRM, or ENTER	Once the desired limit, position, or parameter is visible in the display window, press INCRM, DECRM, or ENTER to toggle into edit mode.  The lowest adjustable digit will flash on and off.
LOCAL	Press the LOCAL key for that device to switch the flashing digit to the next higher digit. In this way, it is possible to rapidly adjust any digit of a multi-digit parameter or limit.

### **Tower Encoder Calibration**



Parameter C must be set to 2000 for the Model 2070B/2071B.

Parameter C, the encoder calibration parameter, is the setting that converts the encoder count values returned from a motor base into the corresponding centimeter or degree position reading. For towers, this represents the number of encoder counts per meter. This parameter allows a variety of standard, retrofit, and custom devices to be used.

If the given value does not work correctly, the encoder calibration value can be determined using the following procedure:

- 1. Set the encoder calibration value to 1000.
- 2. Make sure the tower is positioned to allow at least one meter of travel in the upward direction at an easily measurable height, and then set the current position reading to 000.0. To allow this, you must adjust the lower limit setting.
- 3. Use the STEP keys to adjust the height of the carrier until it is one meter above the start point.
- **4.** Record the reading of the display, ignoring the decimal point. For example, **200.0** would be **2000**. This is the encoder calibration value.



If the value is below 1000, the resolution of the encoder is low and the Model 2090 will not provide 0.1-cm resolution, even though the display shows that digit. If the value is past 9999, the encoder has too many counts per meter and the controller cannot correct for it. In this case, contact ETS-Lindgren for assistance.

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- **5.** Enter the encoder calibration value and reset the limits and position information.
- **6.** Test the tower by moving it a known distance and comparing the display to the measured distance traveled. It may be necessary to adjust the encoder calibration value up or down slightly depending on the result.

# **Mounting Antennas**

The Model 2070B/2071B accepts antennas with the following mount types:

- Stinger mount
- 7/8–14 thread
- 1/4–20 thread

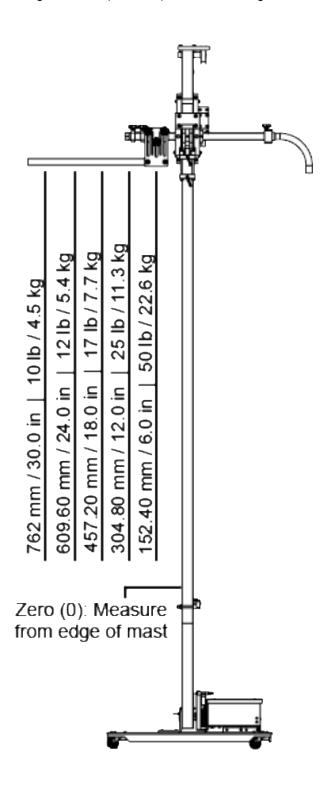
These mount types will maintain the centerline axis during polarization. The antenna should be mounted on the boom as close to the carrier as possible.

Insert the mounting knobs through the holes on the boom and align the mounting holes on the antenna with the threaded end of the mounting knobs. Secure the antenna in place by tightening the threaded knobs into the receptacle mounting holes on the antenna.

# BOOM LOAD LIMITATIONS (MODEL 2070B / MODEL 2071B)



Boom loading at 25 ft lb (33.9 Nm) measured along the boom from the mast.



# Pre-Operational Checklist Verify that the power lines are connected for the tower, controller, and any other equipment to be used for testing. Verify the fiber optic cables are connected. Verify the antenna connected to the boom is securely mounted. Connect the feed cable to the antenna. Before moving the carrier on the mast up or down, verify there are no people standing near the boom. Start-Up and Shutdown

## START-UP



If you are unfamiliar with the operation of the Model 2090 (or next generation ETS-Lindgren controller, if applicable), see the manual included with the controller. The manual is also available for download from <a href="https://www.ets-lindgren.com">www.ets-lindgren.com</a>.

After completing the pre-operational checks, turn on the Model 2090 by pressing the power button.

### **SHUTDOWN**

Move the carrier to an accessible height to remove the antenna and confirm the unit has come to a complete stop. Press the power button on the Model 2090 to turn it off.

# **Appendix A: Warranty**



See the *Product Information Bulletin* included with your shipment for the complete ETS-Lindgren warranty for your Model 2070B or Model 2071B Antenna Positioning Tower.

# **DURATION OF WARRANTIES FOR MODEL 2070B / MODEL 2071B**

All product warranties, except the warranty of title, and all remedies for warranty failures are limited to two years.

Product Warranted	<b>Duration of Warranty Period</b>
Model 2070B Antenna Positioning Tower	2 Years
Model 2071B Antenna Positioning Tower	2 Years

Warranty 45

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# Declaration of Conformity

We, ETS-Lindgren, L.P., 1301 Arrow Point Drive, Cedar Park, TX, 78613, USA, declare under sole responsibility that the:

Model/Part Number: 2175 / 2070B / 2071B

Model/Part Name: 2175 / 2070B / 2071B Antenna Mast with 2175 style motor base

Date of Declaration: 01 May, 2005

to which this declaration relates, meets the requirements and is in conformity with the relevant EC Directives listed below using the relevant section(s) of the following EC harmonized standards and other normative documents;

### Applicable Directive(s):

Low Voltage Directive (LVD), 73/23/EEC and its amending directives

Electomagnetic Compatibility Directive (EMC), 2004/108/EC and its amending directives

### Applicable harmonized standard(s) and/or normative document(s):

EN 55011: Electromagnetic emissions requirements for Industrial, Scientific and Medical (ISM) Equipment

EN 61000-4-11;1994 Electromagnetic compatibility Part 4, Testing and measurement techniques section 11; Voltage dips, short interruptions and voltage variations immunity tests

EN 61000-4-2:1995 Electromagnetic compatibility (EMC) — Part 4-2: Testing and measurement techniques - Electrostatic discharge immunity test

EN 61000-4-3:1997 Electromagnetic compatibility for Electrical and Electronic Equipment, Part 3: Immunity to radiated, radio frequency, electromagnetic fields

EN 61000-4-4:1995 Electromagnetic compatibility for industrial process measurement and control equipment, Part 4: Electrical fast transient/burst requirements

EN 61000-4-5:1995 Electomagnetic compatibility for electrical and electronic equipment. Part 5: Surge immunity requirements

EN 61010-1: Safety requirements for electrical equipment for measurement, control, and laboratory use

ENV 50204:1996 Radiated electromagnetic fields from digital radio telephones - Immunity test

Authorized Signatories:

ETS-Linderen L.P.

Bryan Sayler, General Manage

ETS-Kindgren L.P.

James C. Psencik, Vice President of Engineering

The authorizing signatures on this Declaration of Conformity document authorizes ETS-Lindgren, L.P. to affix the CE mark to the indicated product. CE marks placed on these products will be distinct and visible. Other marks or inscriptions liable to be mistaken with the CE mark will not be affixed to these products.

ETS-Lindgren, L.P. has ensured that technical documentation shall remain available on premises for inspection and validation purposes for a period ending at least 10 years after the last product has been manufactured. This page intentionally left blank.

# **Appendix C: Drawings**

The following drawings are located in the pocket of the back cover of the manual:

114317: MODEL 2070B ANTENNA POSITIONING TOWER (2 PAGES)

114365: MODEL 2070B CARRIER ASSEMBLY (2 PAGES)

108983: MODEL 2070B CROSS BOOM

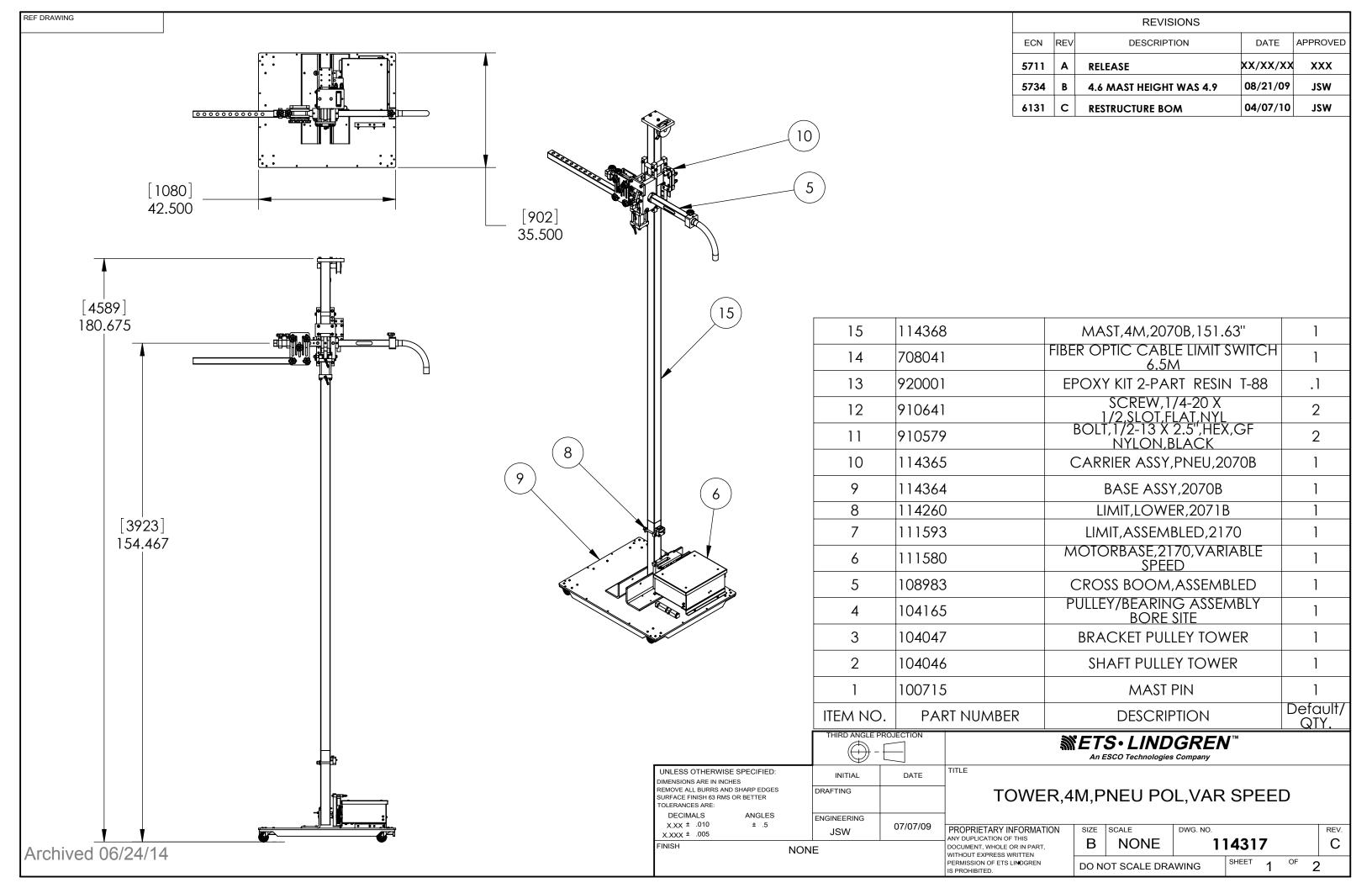
114671: MODEL 2071B ANTENNA POSITIONING TOWER (2 PAGES)

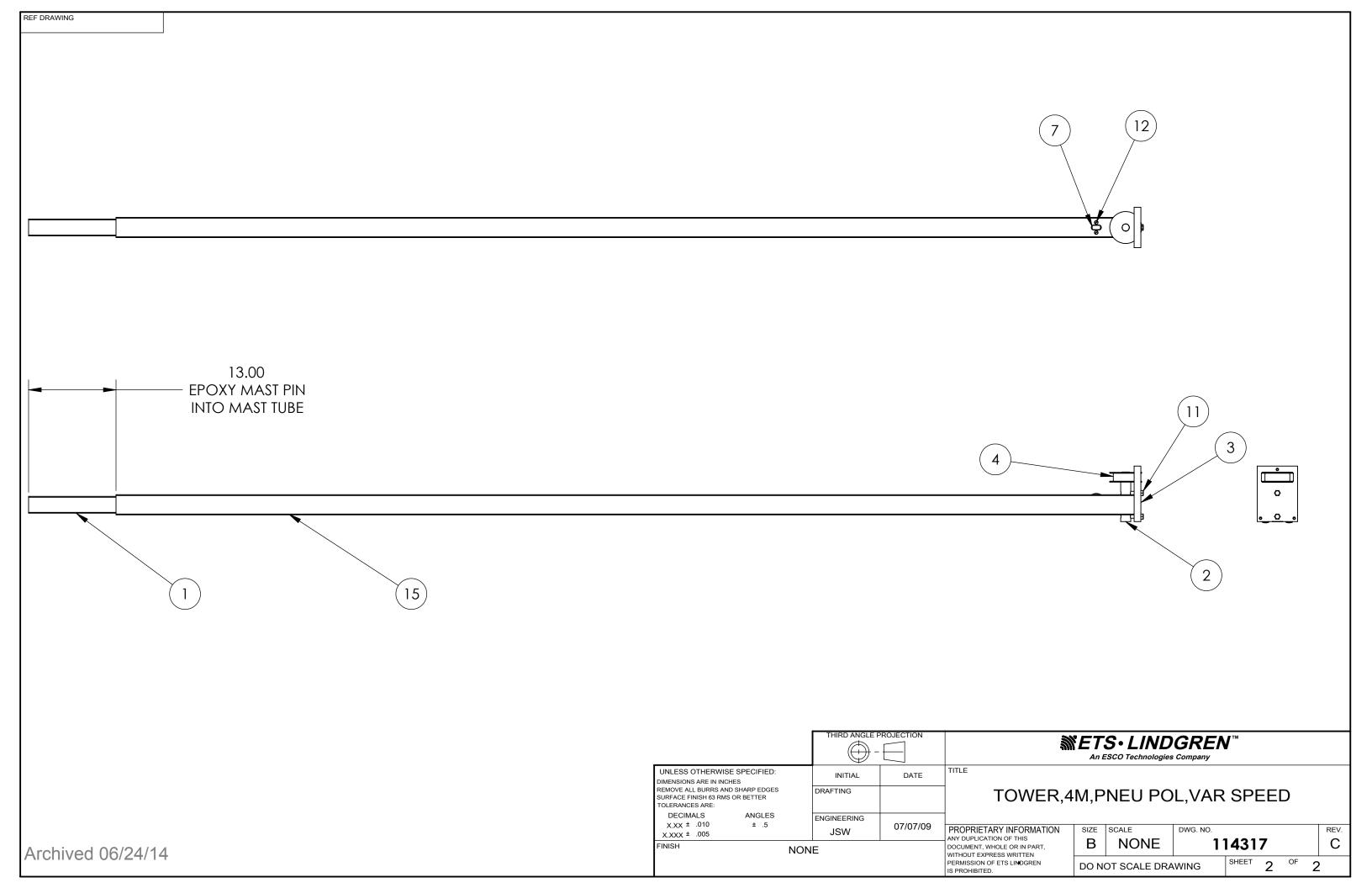
108803: MODEL 2071B BORE SITE CARRIER ASSEMBLY (4 PAGES)

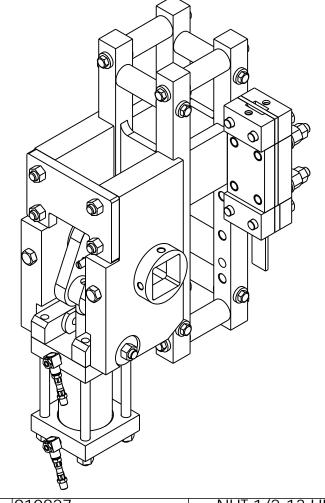
111580: MOTOR BASE (2 PAGES)

**114260: LOWER LIMIT** 

114364: BASE (2 PAGES)







	D		
40	910827	NUT,1/2-13,HEX,FG,BROWN	4
39	910624	SET SCREW, SLTD NYLON, 3/8-16 X 3/4" FLAT	5
38	910591	BOLT,1/2-13 X 1.5",HEX,GF NYLON,BLACK	2
37	910584	NUT,1/2-13,HEX,GF NYLON,BLK	10
36	910582	BOLT,1/2-13 X 2.0",HEX,GF NYLON,BLACK	2
35	910579	BOLT,1/2-13 X 2.5",HEX,GF NYLON,BLACK	8
34	910577	BOLT,3/8-16 X 1.0",HEX,GF NYLON,BLACK	16
33	890477	BUSHING FLAT RUBBER	16
32	890469	HOSE COILED SINGLE 1" 1/4x1/8x30Ft A6460	2
31	890468	CONNECTOR MALE 28-4-2 PARKER	4
30	890464	NUT TUBE 5000-2 CLIPPARD	4
ITEM NO.	PART NUMBER	DESCRIPTION	QTY.

		REVISIONS		
ECN	REV	DESCRIPTION	DATE	APPROVED
5711	Α	RELEASE	XX/XX/XX	XXX

29	880393	BELT,TIMING,T10,25MM,ESD	30
28	105948-2	END PLATE ROTATING BOOM	1
27	105948-1	END PLATE ROTATING BOOM	1
26	105947	SPACER SLEEVE ROTATING BOOM 2070	1
25	105946	BOOM 2070 LONG STUDS 7.50" ROTATING BOOM	4
24	105945	DOWEL PIN .375 X 2.0 PHEN	2
23	105944	CYLINDER ROD PIN ROTATING BOOM	1
22	105943	CYLINDER ROD SLEEVE	1
24	105942	BRACKET PLATE ROTATING BOOM 2070	1
20	105937	BOOM 2070 ARM PIVOT ROTATING BOOM 2070	2
19	105935	2070 BEARING SLEEVE ROTATING BOOM 2070	2
18	105934	DOWEL PIN .50 X 2.0 PHEN	2
17	105827	LOWER CLAMP PLATE TOWER BELT CLAMP	1
16	105826	LOWER TOOTH PLATE TOWER	1
15	105825	BELT CLAMP LOWER THRU PLATE TOWER BELT CLAMP	1
14	105824	CLAMP UPPER THRU PLATE TOWER BELT CLAMP	1
13	105823	CLAMP UPPER MIDDLE CLAMP PLATE TOWER BELT CLAM	1
12	105822	TOWER BELT CLAM UPPER TOOTH PLATE TOWER BELT CLAMP	1
11	104160	STUD 2.375 BORE SIGHT	3
10	104135	WASHER SHOULDER BORE SIGHT	2
9	104036	BLOCK SQUARING ANT CARRIER	2
8	104034	STUD 3.625 ANT CARRIER III	4
7	104027	CLAMP 2 ANT CARRIER III	1
6	104022	ROLLER ANT CARRIER III	8
5	104020	AXLE 2 ANT CARRIER III	8
4	104011	CLAMP 3 ANT CARRIER III	1
3	104010	CLAMP 1 ANT CARRIER III	11
2	104007	PLATE CORNER ANT CARRIER III	2
18	103794	AIR CYLINDER ASSY III	1
ITEM NO.	PART NUMBER	DESCRIPTION	QTY.
THIRD ANGLE PRO	JECTION	<b>METS• LINDGREN</b> ™	

UNLESS OTHERWISE SPECIFIED:
DIMENSIONS ARE IN INCHES
REMOVE ALL BURRS AND SHARP EDGES
SURFACE FINISH 63 RMS OR BETTER
TOLERANCES ARE:
DECIMALS
ANGLES
X.XX ± .010 ± .5
X.XXX ± .005

INITIAL
DATE

INITIAL
DATE

FRAFTING

DRAFTING

O7/14/09

PROPHANY DUR

NONE

FINISH

CARRIER ASSY,PNEU,2070B

An ESCO Technologies Company

PROPRIETARY INFORMATION

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PERMISSION OF ETS LINDGREN
IS PROHIBITED.

 SIZE
 SCALE
 DWG. NO.
 REV.

 B
 NONE
 114365
 A

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